

# Overparametrized Linear Regression under Adversarial Attacks

Antônio Horta Ribeiro

Uppsala University (Sweden)

SIERRA group meeting  
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# Outline

Motivation

Robustness in high-dimensions

Adversarial training

# The state of Minas Gerais and telehealth

- ▶ Minas Gerais



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- ▶ Telehealth center of Minas Gerais
- ▶ More than 4000 ECGs per day



# Electrocardiogram exam and machine learning

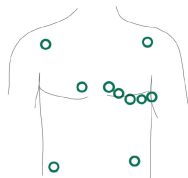
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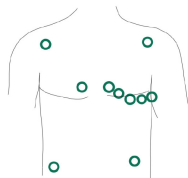
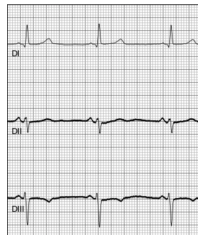


**Left:** ECG signal **Right:** Electrode placement.

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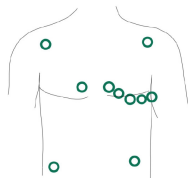


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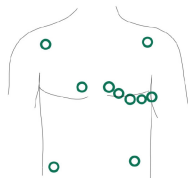
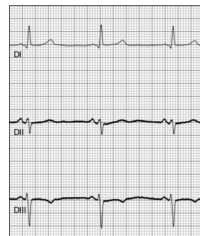
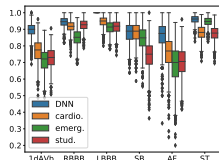


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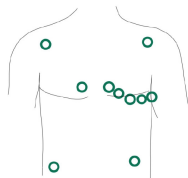
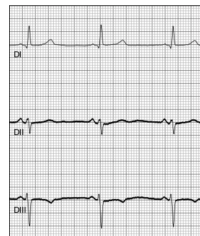
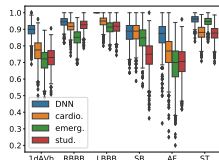


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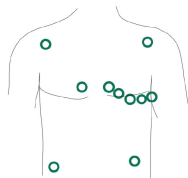
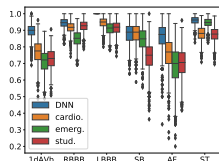


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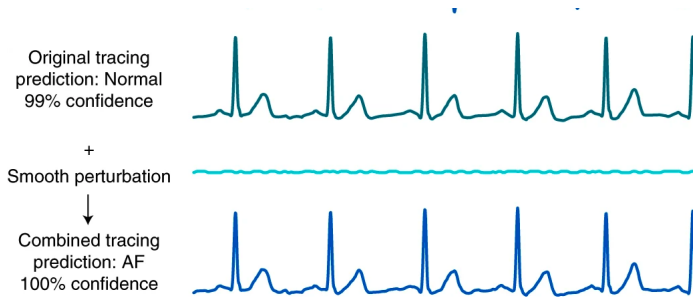
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**A. H. Ribeiro**, M.H. Ribeiro, Paixão, G.M.M., et al. "Automatic diagnosis of the 12-lead ECG using a deep neural network," *Nature Communications*, 2020

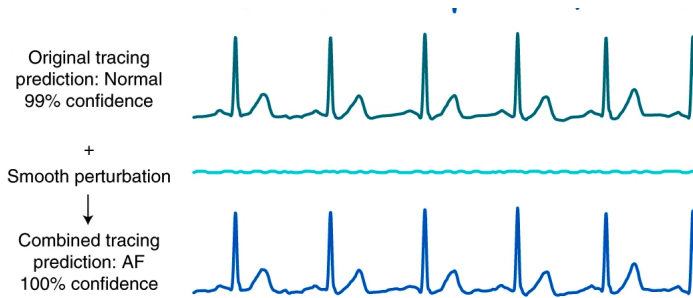
# Adversarial examples



**Figure:** Effect of adversarial examples on ECG Classification.

Source: Han, X., Hu, Y., Foschini, L. et al. Deep learning models for electrocardiograms are susceptible to adversarial attack. *Nature Medicine* 26, 360–363 (2020).

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## Adversarial robustness

*“what is the role of high-dimensionality in model robustness?”*

Overparameterized Linear Regression under Adversarial Attacks (2023). **Antônio H. Ribeiro**, Thomas B. Schön. *IEEE Transactions on Signal Processing* (preprint: [arxiv.org/abs/2204.06274](https://arxiv.org/abs/2204.06274)).

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## Adversarial training

*“How is it connected to other regularization methods?”*

Surprises in adversarially-trained linear regression (2022). **Antônio H. Ribeiro**, Dave Zachariah, Francis Bach, Thomas B. Schön. *Work in progress*.

# Framework: Linear regression

*Simplest case where adversarial vulnerability has been observed.*

I. J. Goodfellow, J. Shlens, C. Szegedy, "Explaining and Harnessing Adversarial Examples", ICLR 2015

D. Tsipras, S. Santurkar, L. Engstrom, A. Turner, and A. Ma, "Robustness May Be At Odds with Accuracy," ICLR, p. 23, 2019.

► Training dataset:

$$(\mathbf{x}_1, \mathbf{y}_1), (\mathbf{x}_2, \mathbf{y}_2), \dots, (\mathbf{x}_n, \mathbf{y}_n) \Rightarrow \hat{\beta}$$

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- ▶ Error( $\hat{\beta}$ ) =  $|\mathbf{y} - \mathbf{x}^T \hat{\beta}|$

- ▶ Adv-error( $\hat{\beta}$ ) =  $\max_{\|\Delta \mathbf{x}\| \leq \delta} |\mathbf{y} - (\mathbf{x} + \Delta \mathbf{x})^T \hat{\beta}|$

## Adversarial error in linear regression

- ▶  $\text{Error}(\hat{\beta}) = |y - \mathbf{x}^T \hat{\beta}|$
- ▶  $\text{Adv-error}(\hat{\beta}) = \max_{\|\Delta \mathbf{x}\| \leq \delta} |y - (\mathbf{x} + \Delta \mathbf{x})^T \hat{\beta}|$
- ▶ *Dual formula for the adversarial error*

$$\left(\text{Adv-error}(\hat{\beta})\right)^2 = \left(|\text{Error}(\hat{\beta})| + \delta \|\hat{\beta}\|_*\right)^2$$

- ▶ where  $\|\cdot\|_*$  is the dual norm.

## $\ell_p$ -adversarial attacks

- ▶  $\ell_\infty$ -adversarial attack:  $\{\|\Delta x\|_\infty \leq \delta\} \Rightarrow$  dual norm:  $\|\Delta x\|_1$

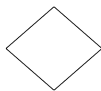


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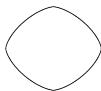
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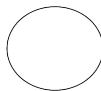
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- ▶  $\ell_p$ -adversarial attack:  $\{\|\Delta x\|_p \leq \delta\} \Rightarrow$  dual norm:  $\|\Delta x\|_q$   
for  $1/p + 1/q = 1$



$\ell_1$



$\ell_{1.5}$



$\ell_2$



$\ell_{20}$



$\ell_\infty$

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## ▶ High-dimensionality as a source of robustness:

S. Bubeck and M. Sellke, "A Universal Law of Robustness via Isoperimetry," Advances in Neural Information Processing Systems, 2021

# How neural networks can perform well?

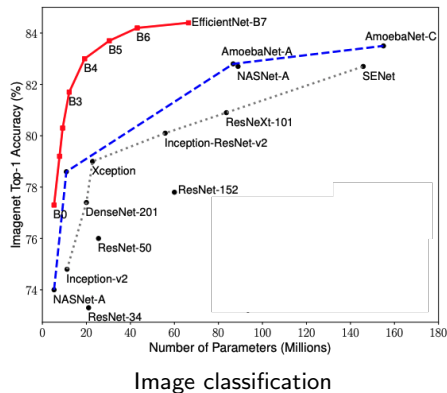
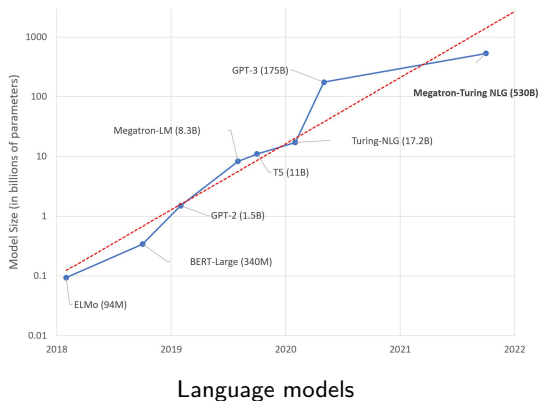


Figure: Models number of parameters

Sources: J. Simon (2021) "Large Language Models: A New Moore's Law?". Online (accessed: 2021-11-09). URL: [huggingface.co/blog/large-language-models](https://huggingface.co/blog/large-language-models).  
M. Tan and Q. V. Le (2019) "EfficientNet: Rethinking Model Scaling for Convolutional Neural Networks," ICML

*Can a model perfectly fit the training data and still generalize well?*

▶ **Benign overfitting**

P. L. Bartlett, P. M. Long, G. Lugosi, and A. Tsigler, "Benign overfitting in linear regression," *Proceedings of the National Academy of Sciences*, vol. 117, no. 48, pp. 30063–30070, Apr. 2020.

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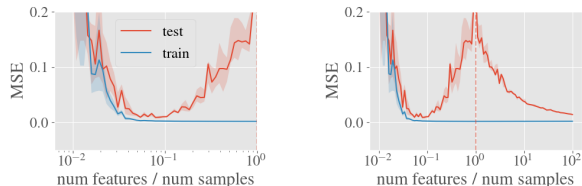
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## ► Example:



**Figure:** nonlinear ARX mean squared error (MSE).

**A. H. Ribeiro**, J. N. Hendriks, A. G. Wills, T. B. Schön. "Beyond Occam's Razor in System Identification: Double-Descent when Modeling Dynamics". *IFAC SYSID 2021*. *Honorable mention: Young author award*

## Setup: minimum-norm interpolator

$$\min_{\beta} \|\beta\|_2 \quad \text{subject to} \quad X\beta = y$$

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## Analysing adversarial robustness

From:

$$\mathbb{E} \left[ \left( \text{Adv-error}(\hat{\beta}) \right)^2 \right] = \mathbb{E} \left[ \left( |\text{Error}(\hat{\beta})| + \delta \|\hat{\beta}\|_* \right)^2 \right]$$

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It follows that:

$$\mathbb{E}[\text{Error}(\hat{\beta})^2] + \delta^2 \|\hat{\beta}\|_*^2 \leq \mathbb{E}[(\text{Adv. error}(\hat{\beta}))^2] \leq 2 \left( \mathbb{E}[\text{Error}(\hat{\beta})^2] + \delta^2 \|\hat{\beta}\|_*^2 \right).$$

## Double-descent in the adversarial loss

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$\|\hat{\beta}\|_2$  also present a double descent behavior: *As we increase the problem dimension, it becomes possible to find solutions with smaller norm.*

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## Asymptotic results

Analysing minimum-norm interpolation:

$$(x_i, \epsilon_i) \sim P_X \times P_\epsilon, \quad y_i = x_i^\top \beta + \epsilon_i,$$

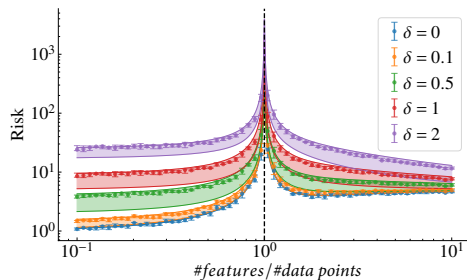


Figure: Adversarial risk vs number of features  $m$ .

T. Hastie, A. Montanari, S. Rosset, and R. J. Tibshirani, "Surprises in High-Dimensional Ridgeless Least Squares Interpolation," *Annals of Statistics*. 50(2): 949-986 (2022).

## High-dimensionality as a source of brittleness

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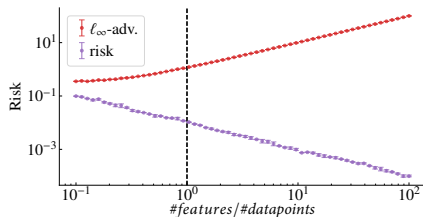
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# Is robustness at odds with accuracy?

When good model become more vulnerable to adversarial attacks as we add features?

## Proposition

If  $\mathbb{E}[\text{Error}(\hat{\beta})^2] < \epsilon$ :

$$\mathbb{E}[(\text{Adv. error}(\hat{\beta}))^2] \rightarrow \infty \quad \text{as} \quad \# \text{features} \rightarrow \infty$$

**if and only if**

$$\delta \|\hat{\beta}\|_* \rightarrow \infty.$$

## Example: optimal predictor vulnerable to adversarial attacks

▶ Optimal predictor:  $\hat{\beta} = \left[ \frac{1}{\#features}, \dots, \frac{1}{\#features} \right]$

▶  $\Delta x = \mathbb{E}\|x\|_2 \propto \sqrt{\#features}$

▶ For our example,

$$\delta \|\hat{\beta}\|_1 = \sqrt{\#features}$$

hence

$$\mathbb{E}[(\ell_{\infty}\text{-adv. error}(\hat{\beta}))^2] = \mathcal{O}(\#features)$$



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### Mismatched example

▶  $\ell_{\infty}$ -adv. attack  $\|\Delta x\|_{\infty} \leq \delta$ .

▶  $\Delta x \propto \mathbb{E} \|x\|_2$ .

:

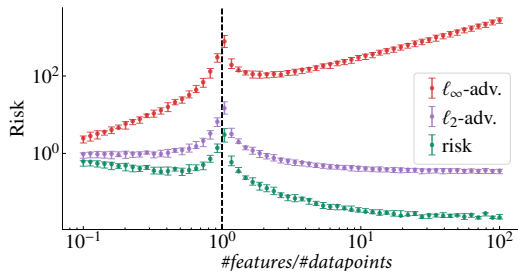
## Example: minimum $\ell_2$ -norm interpolator

Minimum  $\ell_2$ -norm interpolator and Gaussian features:

$$\|\hat{\beta}\|_1 = \mathcal{O}(1) \quad \|\hat{\beta}\|_2 = \mathcal{O}(1/\sqrt{m})$$

Now, if we scale

$$\delta \propto \mathbb{E}\|x\|_2 = \mathcal{O}(\sqrt{m}).$$



**Figure:** Adv. risk.

# The effect of adversarial training and regularization

Empirical risk minimization:

$$\min_{\beta} \frac{1}{n} \sum_{i=1}^n (y_i - \mathbf{x}_i^T \beta)^2$$

Adversarial training:

$$\min_{\beta} \frac{1}{n} \sum_{i=1}^n \max_{\|\Delta \mathbf{x}_i\| \leq \delta} (y_i - (\mathbf{x}_i + \Delta \mathbf{x}_i)^T \beta)^2$$

## The effect of regularization

- ▶ Ridge and  $\ell_2$ -adversarial training

$$\|\hat{\beta}\|_1 = \mathcal{O}(1)$$

- ▶ Lasso,  $\ell_\infty$ -adversarial training

$$\|\hat{\beta}\|_1 = \mathcal{O}(1/\sqrt{m})$$

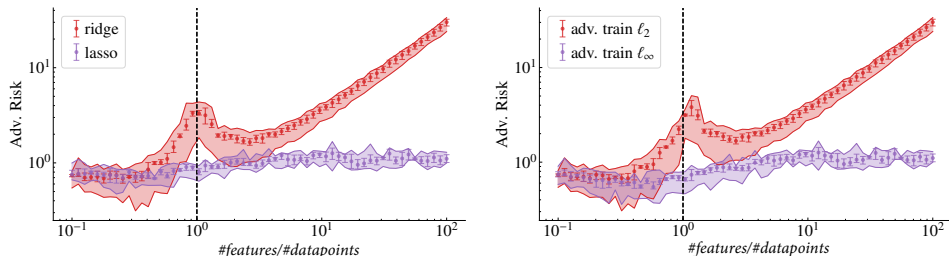
# The effect of regularization

- ▶ Ridge and  $\ell_2$ -adversarial training

$$\|\hat{\beta}\|_1 = \mathcal{O}(1)$$

- ▶ Lasso,  $\ell_\infty$ -adversarial training

$$\|\hat{\beta}\|_1 = \mathcal{O}(1/\sqrt{m})$$



**Figure:** Adversarial  $\ell_\infty$  risk and  $\delta \propto \mathbb{E}\|x\|_2$ .

# Outline

Motivation

Robustness in high-dimensions

Adversarial training

# Adversarial training in linear models

- ▶ Adversarial training,

$$\frac{1}{n} \sum_{i=1}^n \max_{\|\Delta x\| \leq \delta} (y_i - (x_i + \Delta x)^T \beta)^2$$

## Adversarial training in linear models

- ▶ Adversarial training,

$$\frac{1}{n} \sum_{i=1}^n \max_{\|\Delta x\| \leq \delta} (y_i - (x_i + \Delta x)^T \beta)^2$$

can be reformulated as

$$\frac{1}{n} \sum_{i=1}^n \left( |y_i - x_i^T \beta| + \delta \|\beta\|_* \right)^2$$



## Lasso and $\ell_\infty$ -adversarial training

- ▶  $\ell_\infty$ -adversarial training:

$$\frac{1}{n} \sum_{i=1}^n \left( |y_i - \mathbf{x}_i^\top \boldsymbol{\beta}| + \delta \|\boldsymbol{\beta}\|_1 \right)^2$$

- ▶ Lasso:

$$\frac{1}{n} \sum_{i=1}^n \left( |y_i - \mathbf{x}_i^\top \hat{\boldsymbol{\beta}}| \right)^2 + \delta \|\boldsymbol{\beta}\|_1$$

## Ridge regression and $\ell_2$ -adversarial training

- ▶  $\ell_2$ -adversarial training:

$$\frac{1}{n} \sum_{i=1}^n \left( |y_i - \mathbf{x}_i^T \boldsymbol{\beta}| + \delta \|\boldsymbol{\beta}\|_2 \right)^2$$

- ▶ Ridge:

$$\frac{1}{n} \sum_{i=1}^n \left( |y_i - \mathbf{x}_i^T \boldsymbol{\beta}| \right)^2 + \delta \|\boldsymbol{\beta}\|_2^2$$

# Diabetes example

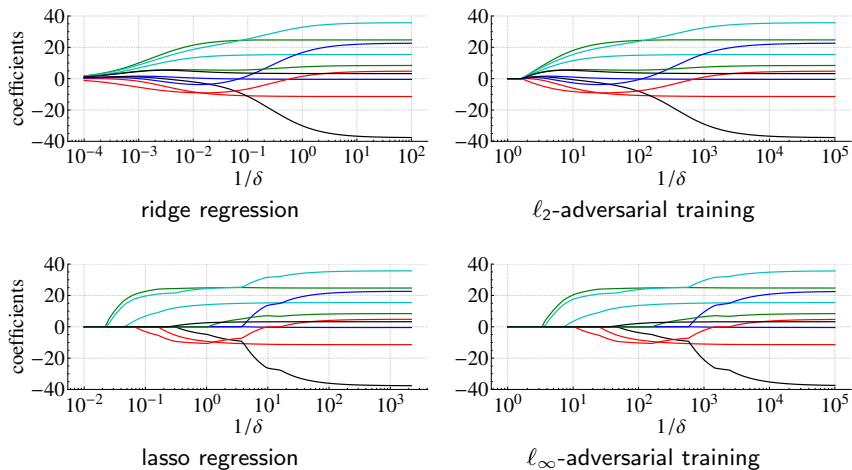


Figure: Regularization paths.

# Minimum-norm solution

## Minimum $\ell_2$ -norm solution

$$\min_{\beta} \|\beta\|_2 \quad \text{subject to} \quad X\beta = y$$

- ▶ Gradient descent in linear regression converges to  $\hat{\beta}^{\text{min-}\ell_2}$ .
- ▶ Used to study *benign overfitting* in:

P. L. Bartlett, P. M. Long, G. Lugosi, and A. Tsigler, "Benign overfitting in linear regression," Proceedings of the National Academy of Sciences, vol. 117, no. 48, pp. 30063–30070, Apr. 2020.

- ▶ Use to study *double descent* in:

M. Belkin, D. Hsu, S. Ma, and S. Mandal, "Reconciling modern machine-learning practice and the classical bias–variance trade-off," PNAS (2019)

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## Minimum $\ell_1$ -norm solution

$$\min_{\beta} \|\beta\|_1 \quad \text{subject to} \quad X\beta = y$$

- ▶ Basis pursuit: i.e. allow you to recover sparse signals.
- ▶ Can also be used to study *benign overfitting* and *double descent*, i.e.,

F. Koehler, L. Zhou, D. J. Sutherland, and N. Srebro, "Uniform Convergence of Interpolators: Gaussian Width, Norm Bounds and Benign Overfitting," presented at the Advances in Neural Information Processing Systems, 2021

# Minimum-norm interpolator and adversarial training

## Theorem

Adversarial training is minimized at the minimum norm interpolator

$$\min_{\beta} \|\beta\|_* \quad \text{subject to} \quad X\beta = y$$

iff  $0 < \delta < \bar{\delta}$ .

Surprises in adversarially-trained linear regression (2022). **Antônio H. Ribeiro**, Dave Zachariah, Francis Bach, Thomas B. Schön. *Work in progress*.

# $\ell_2$ -adversarial training vs ridge regression

## Relation to min-norm solution

- ▶ **(corollary)**  $\hat{\beta}^{\min-\ell_2}$  is the solution to  $\ell_2$ -adversarial training iff  $0 < \delta < \bar{\delta}$ .
- ▶ Ridge  $\hat{\beta}^{\text{ridge}}(\delta) \rightarrow \hat{\beta}^{\min-\ell_2}$  as  $\delta \rightarrow 0^+$ .

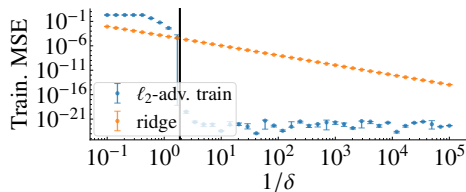


Figure: Training MSE vs regularization parameter.

# $\ell_\infty$ -adversarial training vs Lasso

## Relation to min-norm solution

- ▶ **(corollary)**  $\hat{\beta}^{\min-\ell_1}$  is the solution to  $\ell_\infty$ -adversarial training iff  $0 < \delta < \bar{\delta}$ .
- ▶ Lasso  $\hat{\beta}^{\text{lasso}}(\delta) \rightarrow \hat{\beta}^{\min-\ell_1}$  as  $\delta \rightarrow 0^+$  (LARS algorithm)..

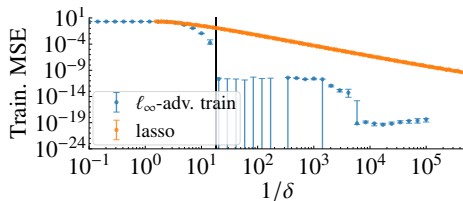


Figure: Training MSE vs regularization parameter.



## Discussion

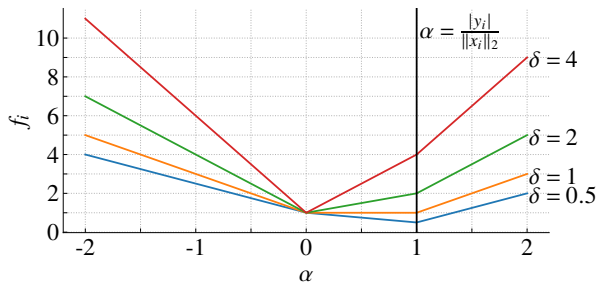
- ▶ Distinct behavior from other parameter shrinking methods (overparametrized).

## Discussion

- ▶ Distinct behavior from other parameter shrinking methods (overparametrized).
- ▶ Explanation for abrupt transitions. Let:

$$f_i(\beta) = |y_i - \mathbf{x}_i^T \beta| + \delta \|\beta\|_2.$$

and assume  $|y_i| = \|\mathbf{x}_i\|_2 = 1$



# New interpretation for minimum-norm interpolator

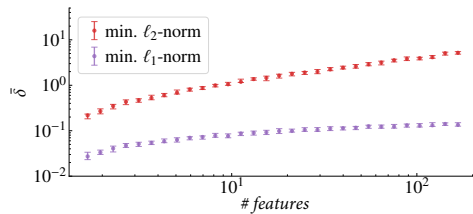


Figure: Threshold  $\bar{\delta}$  vs number of features  $m$ .

# New interpretation for minimum-norm interpolator

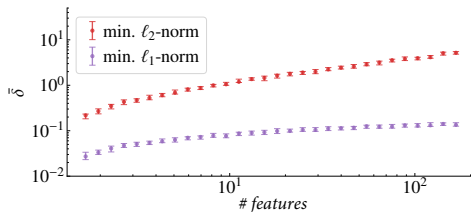


Figure: Threshold  $\bar{\delta}$  vs number of features  $m$ .

- ▶ Setup:  $y_i = \mathbf{x}_i^\top \boldsymbol{\beta} + \epsilon_i$ ,  $\mathbf{x}_i \sim \mathcal{N}(0, r^2 I_m)$  and  $\epsilon_i \sim \mathcal{N}(0, \sigma^2)$
- ▶ Increasing the number of features for minimum-norm interpolators increases the maximum disturbance  $\bar{\delta}$  in the corresponding adversarial training problems.

# Summary

- ▶ Dual formula for the adversarial error:

$$\left(\text{Adv-error}(\hat{\beta})\right)^2 = \left(|\text{Error}(\hat{\beta})| + \delta \|\hat{\beta}\|_*\right)^2$$

- ▶ Consequences to adversarial robustness
  - ▶ Simplify analysis of adversarial robustness:

$$\mathbb{E} \left[ \left(\text{Adv-error}(\hat{\beta})\right)^2 \right] \propto \mathbb{E} \left[ \text{Error}(\hat{\beta})^2 \right] + \delta \|\hat{\beta}\|_*^2$$

- ▶ Double descent can be observed in adversarial scenarios.
  - ▶ Sufficient and necessary conditions for good models to be vulnerable to adversary.
- ▶ Consequences to adversarial training:
  - ▶ Convex formula / Similarities with parameter shrink methods
  - ▶  $\ell_\infty$ -adversarial training  $\Rightarrow$  sparse solutions
  - ▶ Can interpolate for disturbance bounded by  $\delta > 0$ .

**Thank you!**

📍 INRIA de Paris - Room C407 (from now to mid-June)

✉ antonio.horta.ribeiro@it.uu.se

🌐 antonior92.github.io